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## LETTER TO THE EDITOR

# Soliton interactions (for the Korteweg-deVries equation): a new perspective 

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#### Abstract

It can be shown that the $N$-soliton solution of the Korteweg-deVries equation can be decomposed into $N$ separate solitons (cf Gardner et al, Calogero and Degasperis and Yoneyama). However, it is not immediately clear from the form of their solutions how the separate solitons relate directly to the single soliton solution. Here the two-soliton case is considered and a decomposition is sought which can be clearly related to the single soliton solution. Although it appears that there is a family of such decompositions it is shown that only one of these is correct. Although this decomposition is equivalent to the decomposition given previously by Gardner et al, Calogero and Degasperis and Yoneyama, the form given here is different. It is suggested that the form of solution produced here is a more appropriate representation of the solution since it is clear how it relates directly to the single soliton solution and it is easy, through this form, to analyse the interaction of the two solitons.


The well known solitary wave or soliton solution of the Korteweg-deVries equation

$$
\begin{equation*}
u_{1}+6 u u_{x}+u_{x x x}=0 \tag{1}
\end{equation*}
$$

is

$$
u=2 a^{2} \operatorname{sech}^{2}(\theta)
$$

where

$$
\begin{equation*}
\theta=a x-4 a^{3} t \tag{2}
\end{equation*}
$$

(cf Dodd et al (1982) p 11, where the equation and solution are written in slightly different form).

The solution (2) yields the conservation property that

$$
\begin{equation*}
\int_{-\infty}^{\infty} u \mathrm{~d} x=4 a . \tag{3a}
\end{equation*}
$$

We define the path of the soliton as the function $x(t)$ such that

$$
\begin{equation*}
\int_{-\infty}^{x(r)} u \mathrm{~d} x=\int_{x(1)}^{\infty} u \mathrm{~d} x=2 a \tag{3b}
\end{equation*}
$$

so that at any point along the path equal portions of the soliton are on either side of the point $x(t)$. It is clear, for the function $u$ as given by expression (2), that ( $3 b$ ) is satisfied by that $x(t)$ for which $\theta=0$. Hence the path is given by putting the argument of the sech $^{2}$ function in (2) equal to zero.

Hirota (1971) showed how to find multi-soliton solutions of the KdV equation and following his method the two-soliton solution is

$$
\begin{equation*}
u=2\left(f f_{x x}-f_{x}^{2}\right) / f^{2} \tag{4a}
\end{equation*}
$$

where

$$
\begin{align*}
& f=1+\exp \left(2 \theta_{1}\right)+\exp \left(2 \theta_{2}\right)+A \exp \left(2 \theta_{1}+2 \theta_{2}\right)  \tag{4b}\\
& \theta_{1}=a_{1} x-4 a_{1}^{3} t \quad \theta_{2}=a_{2} x-4 a_{2}^{3} t \\
& A=\left[\left(a_{1}-a_{2}\right) /\left(a_{1}+a_{2}\right)\right]^{2} .
\end{align*}
$$

Consider a decomposition of the solution $u$, i.e.

$$
\begin{equation*}
u=u_{1}+u_{2} . \tag{5}
\end{equation*}
$$

Although there are infinitely many ways to choose $u_{1}$ and $u_{2}$ one looks for choices such that both $u_{1}$ and $u_{2}$ have a form similar to expression (2). A possible choice of this type is

$$
\begin{align*}
& u_{1}=2 a_{1}^{2} H\left(\theta_{2}\right) \operatorname{sech}^{2}\left[\theta_{1}+G\left(\theta_{2}\right)\right]  \tag{6a}\\
& u_{2}=2 a_{2}^{2} H\left(\theta_{1}\right) \operatorname{sech}^{2}\left[\theta_{2}+G\left(\theta_{1}\right)\right] \tag{6b}
\end{align*}
$$

where the expressions ( $6 a$ ) and ( $6 b$ ) for $u_{1}$ and $u_{2}$ are more general forms of expression (2). These generalisations involve a variable amplitude and a variable phase shift.

Furthermore the variation of $u_{1}$ from a single soliton is entirely due to $\theta_{2}$, the characteristic of $u_{2}$. Likewise the variation of $u_{2}$ from a single soliton is entirely due to $\theta_{1}$, the characteristic of $u_{1}$. Hence the deviation of $u_{1}$ from a single soliton behaviour is due to the presence of $u_{2}$ and vice versa for $u_{2}$. One would expect that when $u_{1}$ and $u_{2}$ are well separated these effects would diminish, i.e. $H\left(\theta_{1}\right)$ and $H\left(\theta_{2}\right)$ would tend to unity and $G\left(\theta_{1}\right)$ and $G\left(\theta_{2}\right)$ would tend to constant values.

It is possible to find a family of such function pairs (cf the appendix) with the phase shift and amplitude factors, in ( $6 a$ ) and ( $6 b$ ), given by

$$
\begin{align*}
& H\left(\theta_{1}\right)=\frac{1+B_{1} \exp \left(2 \theta_{1}\right)+A \exp \left(4 \theta_{1}\right)}{1+(1+A) \exp \left(2 \theta_{1}\right)+A \exp \left(4 \theta_{1}\right)}  \tag{7}\\
& H\left(\theta_{2}\right)=\frac{1+B_{2} \exp \left(2 \theta_{2}\right)+A \exp \left(4 \theta_{2}\right)}{1+(1+A) \exp \left(2 \theta_{2}\right)+A \exp \left(4 \theta_{2}\right)} \\
& G\left(\theta_{1}\right)=\frac{1}{2} \ln \left(\frac{1+A \exp \left(2 \theta_{1}\right)}{1+\exp \left(2 \theta_{1}\right)}\right) \\
& G\left(\theta_{2}\right)=\frac{1}{2} \ln \left(\frac{1+A \exp \left(2 \theta_{2}\right)}{1+\exp \left(2 \theta_{2}\right)}\right)
\end{align*}
$$

where $B_{1}$ and $B_{2}$ are arbitrary constants obeying the constraint

$$
\begin{equation*}
a_{1}^{2} B_{2}+a_{2}^{2} B_{1}=2\left(a_{1}-a_{2}\right)^{2} \tag{8}
\end{equation*}
$$

From the range of possible choices for $B_{1}$ and $B_{2}$ the most obvious choice appears to be

$$
\begin{equation*}
B_{1}=\left(\frac{a_{1}-a_{2}}{a_{2}}\right)^{2} \quad B_{2}=\left(\frac{a_{1}-a_{2}}{a_{1}}\right)^{2} \tag{9}
\end{equation*}
$$

However, an additional constraint on the values of $B_{1}$ and $B_{2}$ is that the expressions $u_{1}$ and $u_{2}$ given in ( $6 a$ ) and ( $6 b$ ) should satisfy the conservation property ( $3 a$ ), i.e.

$$
\begin{align*}
& \int_{-\infty}^{\infty} u_{1} \mathrm{~d} x=4 a_{1}  \tag{10a}\\
& \int_{-\infty}^{\infty} u_{2} \mathrm{~d} x=4 a_{2} \tag{10b}
\end{align*}
$$

We therefore need to test whether $B_{1}$ and $B_{2}$ as given by (9) lead to expressions for $u_{1}$ and $u_{2}$ such that ( $10 a$ ) and ( $10 b$ ) are satisfied. To do this we use expressions (A1) and (4b) to rewrite $u_{1}$ given by ( $6 a$ ), as

$$
\begin{equation*}
u_{1}=\frac{8 a_{1}^{2} \exp \left(2 \theta_{1}\right)\left[1+B_{2} \exp \left(2 \theta_{2}\right)+A \exp \left(4 \theta_{2}\right)\right]}{\left[1+\exp \left(2 \theta_{1}\right)+\exp \left(2 \theta_{2}\right)+A \exp \left(2 \theta_{1}+2 \theta_{2}\right)\right]^{2}} \tag{11}
\end{equation*}
$$

Expression (11) can be rewritten as

$$
\begin{align*}
u_{1}= & \frac{8 a_{1}^{2} \exp \left(2 \theta_{1}\right)\left[1+2 A^{1 / 2} \exp \left(2 \theta_{2}\right)+A \exp \left(4 \theta_{2}\right)\right]}{\left[1+\exp \left(2 \theta_{1}\right)+\exp \left(2 \theta_{2}\right)+A \exp \left(2 \theta_{1}+2 \theta_{2}\right)\right]^{2}} \\
& +\frac{8 a_{1}^{2} \exp \left(2 \theta_{1}+2 \theta_{2}\right)\left[B_{2}-2 A^{1 / 2}\right]}{\left[1+\exp \left(2 \theta_{1}\right)+\exp \left(2 \theta_{2}\right)+A \exp \left(2 \theta_{1}+2 \theta_{2}\right)\right]^{2}} \tag{12}
\end{align*}
$$

Expression (12) may also be rewritten as

$$
\begin{gather*}
u_{1}=4 a_{1} \frac{\delta}{\delta x}\left(\frac{\exp \left(2 \theta_{1}\right)+A \exp \left(2 \theta_{1}+2 \theta_{2}\right)}{1+\exp \left(2 \theta_{1}\right)+\exp \left(2 \theta_{2}\right)+A \exp \left(2 \theta_{1}+2 \theta_{2}\right)}\right) \\
+8 a_{1}^{2} F\left(\theta_{1}, \theta_{2}\right)\left[B_{2}-2 A^{1 / 2}\right] \tag{13}
\end{gather*}
$$

where

$$
\begin{equation*}
F\left(\theta_{1}, \theta_{2}\right)=\exp \left(2 \theta_{1}+2 \theta_{2}\right) /\left[1+\exp \left(2 \theta_{1}\right)+\exp \left(2 \theta_{2}\right)+A \exp \left(2 \theta_{1}+2 \theta_{2}\right)\right]^{2} \tag{14}
\end{equation*}
$$

Note that $F\left(\theta_{1}, \theta_{2}\right)>0$ in all parts of the $x t$ plane. Then

$$
\begin{equation*}
\int_{-\infty}^{\infty} u_{1} \mathrm{~d} x=4 a_{1}+8 a_{1}^{2}\left(B_{2}-2 A^{1 / 2}\right) \int_{-\infty}^{\infty} F\left(\theta_{1}, \theta_{2}\right) \mathrm{d} x \tag{15}
\end{equation*}
$$

so that expression (10a) is satisfied only if

$$
\begin{equation*}
B_{2}=2 A^{1 / 2} \tag{16}
\end{equation*}
$$

Similarly, expression (10b) is satisfied only if

$$
\begin{equation*}
B_{1}=-2 A^{1 / 2} \tag{17}
\end{equation*}
$$

One therefore sees that the, apparently obvious, choice (9) for $B_{1}$ and $B_{2}$ is not possible since the conservation properties ( $10 a$ ) and (10b) are not satisfied in this case. It therefore transpires that the only possible choices for $B_{1}$ and $B_{2}$ are those given by expressions (16) and (17).

The solution $u$ as given by expressions (5)-(7) with $B_{1}, B_{2}$ given by expression (16), (17) is identical to the solution for this problem previously derived by Gardner et al (1974) through the inverse scattering method (cf also Calogero and Degasperis (1982) § 3.2.1) and separately by Yoneyama (1984).

However, the form of the solution given here is different to the forms of previous solutions and preferable in the sense that it is clear how the solution (as given by expressions (5) and ( $6 a$ ) and (b)) relates to the single soliton solution (2). It is also shown subsequently that it is possible to easily analyse the interaction of the two solitons using the form of the solution given here.

For definiteness we consider the case $a_{1}>a_{2}>0$. Note that expression (5) for $u$ is the sum of two terms where each term has the form of a modified soliton in the sense that the first term represents a soliton in the variable $\theta_{1}$ when $\theta_{2}$ is constant while the second term represents a soliton in the variable $\theta_{2}$ when $\theta_{1}$ is constant. It is therefore to be expected that (5) should yield the sum of two solitons as $t \rightarrow \pm \infty$ by considering the asymptotic behaviour of the first term of (5) for any fixed $\theta_{1}$ (as $t \rightarrow \pm \infty$ ) and the asymptotic behaviour of the second term of (5) for any fixed $\theta_{2}($ as $t \rightarrow \pm \infty)$. The limits are: for fixed $\theta_{1}, \theta_{2} \rightarrow-\infty$ as $t \rightarrow-\infty$ and $\theta_{2} \rightarrow \infty$ as $t \rightarrow \infty$ (since $a_{1}>a_{2}$ ); for fixed $\theta_{2}$, $\theta_{1} \rightarrow \infty$ as $t \rightarrow-\infty$ and $\theta_{1} \rightarrow-\infty$ as $t \rightarrow \infty$ (since $a_{1}>a_{2}$ ).

The asymptotic behaviour of $u$, as given by (5), under the above limiting procedure is then

$$
\begin{align*}
& u_{1}(t \rightarrow-\infty) \sim 2 a_{1}^{2} \operatorname{sech}^{2}\left(\theta_{1}\right)  \tag{18a}\\
& u_{2}(t \rightarrow-\infty) \sim 2 a_{2}^{2} \operatorname{sech}^{2}\left[\theta_{2}+\frac{1}{2} \ln A\right]  \tag{18b}\\
& u_{1}(t \rightarrow \infty) \sim 2 a_{1}^{2} \operatorname{sech}^{2}\left[\theta_{1}+\frac{1}{2} \ln A\right]  \tag{19a}\\
& u_{2}(t \rightarrow \infty) \sim 2 a_{2}^{2} \operatorname{sech}^{2}\left(\theta_{2}\right) \tag{19b}
\end{align*}
$$

Expressions (18a)-(19b) summarise the behaviour of the two solitons. As $t \rightarrow-\infty, u_{1}$, with larger magnitude ( $2 a_{1}^{2}$ ) and larger phase speed ( $4 a_{1}^{2}$ ) lies on the $x$ axis at $x=4 a_{1}^{2} t$ which is further to the left than $u_{2}$, with magnitude ( $2 a_{2}^{2}$ ) and phase speed ( $4 a_{2}^{2}$ ) which lies at $x=4 a_{2}^{2} t-\ln A / 2 a_{2}$ on the $x$ axis. As $t \rightarrow+\infty, u_{1}$ lies at $x=4 a_{1}^{2} t-\ln A / 2 a_{1}$ on the $x$ axis which is to the right of $u_{2}$ which is at $x=4 a_{2}^{2} t$ on the $x$ axis. The two solitons, $u_{1}$ and $u_{2}$, have the same form and speed as $t \rightarrow-\infty$ and as $t \rightarrow \infty$ as they would have if they were single solitons. The only effect on them over time is that $u_{1}$ has undergone a phase shift of $-\frac{1}{2} \ln A$ forward along the $\theta_{1}$ axis while $u_{2}$ has undergone a phase shift of $-\frac{1}{2} \ln A$ backward along the $\theta_{2}$ axis.

By direct analogy with (3b) the path of soliton $u_{1}$ is given from ( $6 a$ ) by putting the argument of the $\operatorname{sech}^{2}$ function equal to zero, i.e.

$$
\theta_{1}=-\frac{1}{2} \ln \left[\left(1+A \exp \left(2 \theta_{2}\right)\right) /\left(1+\exp \left(2 \theta_{2}\right)\right)\right]
$$

which may be rewritten as

$$
\begin{equation*}
\exp \left(2 \theta_{1}\right)=\left[1+\exp \left(2 \theta_{2}\right)\right] /\left[1+A \exp \left(2 \theta_{2}\right)\right] \tag{20}
\end{equation*}
$$

In expression (20) $t$ should be considered as the independent variable and $x$ the dependent variable, i.e. $x=x_{1}(t)$ where $x_{1}(t)$ is the solution of (20). The function $x_{1}(t)$ also satisfies the analogous expression to ( $3 b$ ), i.e.

$$
\begin{equation*}
\int_{-\infty}^{x_{1}(t)} u_{1} \mathrm{~d} x=\int_{x_{1}(t)}^{\infty} u_{1} \mathrm{~d} x=2 a_{1} . \tag{21}
\end{equation*}
$$

In a similar way the path of the soliton $u_{2}$ is given by

$$
\begin{equation*}
\exp \left(2 \theta_{2}\right)=\left[1+\exp \left(2 \theta_{1}\right)\right] /\left[1+A \exp \left(2 \theta_{1}\right)\right] . \tag{22}
\end{equation*}
$$

If the interaction point of the solitons is defined as the point of intersection of their paths, this point is given (from (20) and (22)) by

$$
\begin{equation*}
\theta_{1}=\theta_{2}=-\frac{1}{4} \ln A \tag{23}
\end{equation*}
$$

When expression (23) is solved for $x$ and $t$ the interaction point is found to be

$$
\begin{equation*}
x=-\frac{1}{4}\left(a_{1}^{2}+a_{1} a_{2}+a_{2}^{2}\right) \ln A /\left[a_{1} a_{2}\left(a_{1}+a_{2}\right)\right] \quad t=-\frac{1}{16} \ln A /\left[a_{1} a_{2}\left(a_{1}+a_{2}\right)\right] . \tag{24}
\end{equation*}
$$

The paths of the solitons as given by expressions (20) and (22) are shown in figure 1. Note the paths are symmetric about the interaction point given by expression (23). Substituting expression (23) into expressions (5) and ( $6 a$ ) and ( $6 b$ ) gives $u=2\left(a_{1}^{2}-a_{2}^{2}\right)$ so that at the interaction point the amplitude of the 'double' soliton is the difference of the asymptotic amplitudes of the two separate solitons. Note that two solitons of nearly equal phase speeds (and hence magnitudes) almost annihilate each other at the interaction point. Also the amplitude of the slower soliton is reduced to zero at the interaction point. As is clearly shown in figure 1 the slower soliton moves backwards while the faster soliton accelerates forwards near the interaction point.


Figure 1. The paths of the solitons are shown in the $x t$ plane. The path of one soliton is the broken curve and that of the other is the dotted curve. Also shown are the $\theta_{1}$ and $\theta_{2}$ axes and the asymptotes of the paths. The arrows indicate the directions of motion along the paths.

It is instructive to consider the following extreme cases: (1) $a_{2} \rightarrow 0$, i.e. $a_{2} \ll a_{1}$ and (2) $a_{2} \rightarrow a_{1}$.

Case (1) is given by $a_{2}=\varepsilon a_{1}$ where $0<\varepsilon \ll 1$ so that the interaction point ( $x, t$ ) as given by expression (24) becomes $x \rightarrow 1 / a_{1}$ and $t \rightarrow \frac{1}{4} / a_{1}^{3}$ or alternatively on using expression (23) the interaction point $\theta_{1}=\theta_{2}=-\frac{1}{4} \ln A$ becomes $\theta_{1}=\theta_{2}=2 \varepsilon$ which gives a point near the origin in the $\left(\theta_{1}, \theta_{2}\right)$ plane.

Case (2) is given by $a_{2}=a_{1}(1-\varepsilon)$ where $0<\varepsilon \ll 1$ so that the interaction point $(x, t)$ as given by expression (24) becomes $x \rightarrow-3 \ln \left(\frac{1}{2} \varepsilon\right) / 4 a_{1}$ and $t \rightarrow-\ln \left(\frac{1}{2} \varepsilon\right) / 16 a_{1}^{3}$ which give very large positive values for both $x$ and $t$. Alternatively on using expression (23) the interaction point $\theta_{1}=\theta_{2}=-\frac{1}{4} \ln A$ becomes $\theta_{1}=\theta_{2}=-\frac{1}{2} \ln \left(\frac{1}{2} \varepsilon\right)$ which also gives very large positive values for $\theta_{1}$ and $\theta_{2}$.

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## Appendix

Expression (4) for $u$ can be rearranged as follows: expression (4b) gives

$$
\begin{gathered}
f f_{x x}-f_{x}^{2}=4\left[a_{1}^{2} \exp \left(2 \theta_{1}\right)+a_{2}^{2} \exp \left(2 \theta_{2}\right)+2\left(a_{1}-a_{2}\right)^{2} \exp \left(2 \theta_{1}+2 \theta_{2}\right)\right. \\
\left.+a_{2}^{2} A \exp \left(4 \theta_{1}+2 \theta_{2}\right)+a_{1}^{2} A \exp \left(2 \theta_{1}+4 \theta_{2}\right)\right]
\end{gathered}
$$

which can be rewritten as

$$
\begin{equation*}
f f_{x x}-f_{x}^{2}=4 a_{1}^{2} p\left(\theta_{2}\right) \exp \left(2 \theta_{1}\right)+4 a_{2}^{2} p\left(\theta_{1}\right) \exp \left(2 \theta_{2}\right) \tag{A1}
\end{equation*}
$$

where

$$
\begin{align*}
& p\left(\theta_{2}\right)=1+B_{2} \exp \left(2 \theta_{2}\right)+A \exp \left(4 \theta_{2}\right) \\
& p\left(\theta_{1}\right)=1+B_{1} \exp \left(2 \theta_{1}\right)+A \exp \left(4 \theta_{1}\right) \\
& a_{2}^{2} B_{1}+a_{1}^{2} B_{2}=2\left(a_{1}-a_{2}\right)^{2} . \tag{A2}
\end{align*}
$$

Expression (4b) also gives

$$
\begin{align*}
f^{2}=[1+\exp ( & \left.\left.2 \theta_{1}\right)\right]^{2}+2\left[1+\exp \left(2 \theta_{1}\right)\right]\left[\exp \left(2 \theta_{2}\right)+A \exp \left(2 \theta_{1}+2 \theta_{2}\right)\right] \\
& +\left[\exp \left(2 \theta_{2}\right)+A \exp \left(2 \theta_{1}+2 \theta_{2}\right)\right]^{2} \\
= & {\left[1+\exp \left(2 \theta_{1}\right)\right]\left[1+A \exp \left(2 \theta_{1}\right)\right] \exp \left(2 \theta_{2}\right) } \\
& \times\left[\left(\frac{1+\exp \left(2 \theta_{1}\right)}{1+A \exp \left(2 \theta_{1}\right)}\right) \exp \left(-2 \theta_{2}\right)+2+\left(\frac{1+A \exp \left(2 \theta_{1}\right)}{1+\exp \left(2 \theta_{1}\right)}\right) \exp \left(2 \theta_{2}\right)\right] \\
= & 4 q\left(\theta_{1}\right) \exp \left(2 \theta_{2}\right) \cosh ^{2}\left[\theta_{2}+G\left(\theta_{1}\right)\right] \tag{A3}
\end{align*}
$$

where
$q\left(\theta_{1}\right)=\left[1+\exp \left(2 \theta_{1}\right)\right]\left[1+A \exp \left(2 \theta_{1}\right)\right]=1+(1+A) \exp \left(2 \theta_{1}\right)+A \exp \left(4 \theta_{1}\right)$
and

$$
G\left(\theta_{1}\right)=\frac{1}{2} \ln \left[\left(1+A \exp \left(2 \theta_{1}\right)\right) /\left(1+\exp \left(2 \theta_{1}\right)\right)\right]
$$

Since expression (4b) for $f$ is symmetric in $\theta_{1}$ and $\theta_{2}$ therefore expression (A3) for $f^{2}$ can be rewritten, by interchanging $\theta_{1}$ and $\theta_{2}$, to obtain

$$
\begin{equation*}
f^{2}=4 q\left(\theta_{2}\right) \exp \left(2 \theta_{1}\right) \cosh ^{2}\left[\theta_{1}+G\left(\theta_{2}\right)\right] \tag{A4}
\end{equation*}
$$

Then substituting expressions (A1) and (A3) or (A4) as appropriate into expression (4a) for $u$ gives
$u=\frac{2 a_{1}^{2} p\left(\theta_{2}\right) \exp \left(2 \theta_{1}\right)}{q\left(\theta_{2}\right) \exp \left(2 \theta_{1}\right) \cosh ^{2}\left[\theta_{1}+G\left(\theta_{2}\right)\right]}+\frac{2 a_{2}^{2} p\left(\theta_{1}\right) \exp \left(2 \theta_{2}\right)}{q\left(\theta_{1}\right) \exp \left(2 \theta_{2}\right) \cosh ^{2}\left[\theta_{2}+G\left(\theta_{1}\right)\right]}$
which is expression (5), on using ( $6 a$ ) and ( $6 b$ ), for $u$ as given earlier.
Note that since $B_{1}$ and $B_{2}$ are not, as yet, fixed in (A2) there is a family of solutions of type (A5).

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